

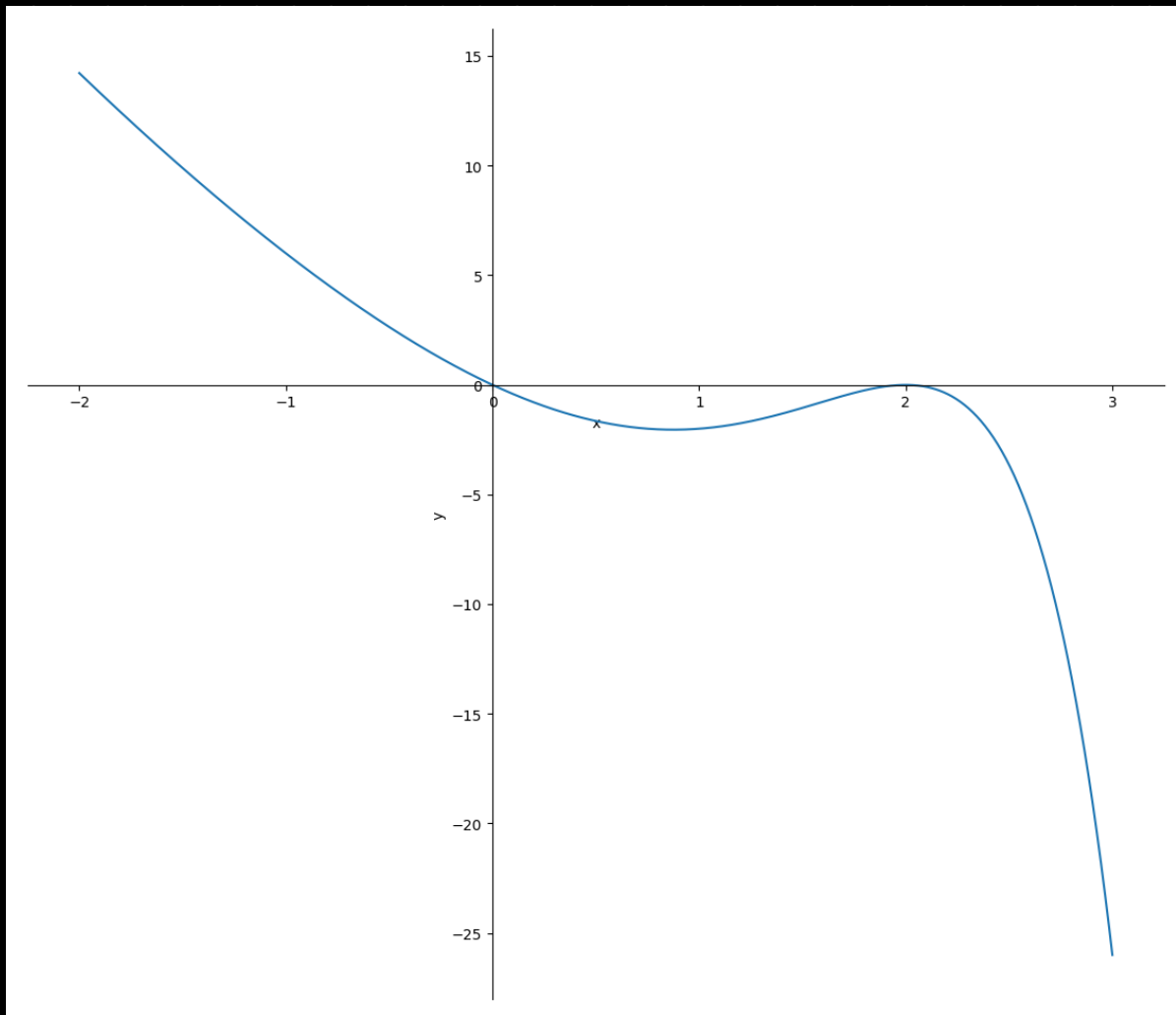
# Matte 4D - Exercise 4

Problem 1 Consider

$$f(x) = (1 - 3^x)x^2 + 4(x - 1)3^x + 4(1 - x).$$

We wish to find the roots on  $[-2, 3]$ ,  
i.e. all  $r$  with  $f(r) = 0$ .

a) The function looks like this:



b) Recall: The bisection method involves repeatedly finding the midpoint of your two nodes to get closer and closer to a root.

First iteration:

$$\frac{a+b}{2} = \frac{-2+3}{2} = \underline{\frac{1}{2}}$$

$$\begin{aligned} f(1/2) &= (1-\sqrt{3}) \cdot \frac{1}{2^2} + 4\left(\frac{1}{2}-1\right)\sqrt{3} + 4\left(1-\frac{1}{2}\right) \\ &= \underbrace{\frac{1}{4}(1-\sqrt{3})}_{<0} - \underbrace{2\sqrt{3}}_{<0} + 2 < 0 \end{aligned}$$

and from the graph we see that  $f(a) > 0$  and  $f(b) < 0$ , so we choose  $1/2$  as a new right-endpoint.

Second iteration:

$$\frac{-2 + 1/2}{2} = \underline{-\frac{3}{4}} \rightarrow f(-\frac{3}{4}) > 0$$

Third iteration:

$$\frac{-3/4 + 1/2}{2} = \underline{-\frac{1}{8}} \rightarrow f(-\frac{1}{8}) > 0$$

Fourth iteration:

$$\frac{-1/8 + 1/2}{2} = \frac{3}{16} = \tilde{x}$$

Since  $f(0) = 0$ , the error is simply

$$\frac{3}{16} - 0 = \underline{\underline{\frac{3}{16}}}$$

C) Recall:  $E \leq \frac{1}{2^{k+1}}(b-a)$  for bisection method

We want to solve for  $k$  in

$$\frac{1}{2^{k+1}}(2+3) \leq 10^{-3}$$

$$\Leftrightarrow 2^{k+1} \geq \frac{5}{10^{-3}} = 5 \cdot 10^3 = 5000$$

$$\Leftrightarrow k+1 \geq \log_2 5000$$

$$k \geq \log_2 5000 - 1$$

$$\approx \underline{\underline{11.3}}$$

So after approximately 12 iterations, we achieve the desired

d) Try  $x = 2$ :

$$\begin{aligned} f(2) &= (1-3^2)2^2 + 4(2-1)3^2 + 4(1-2) \\ &= -8 \cdot 4 + 4 \cdot 1 \cdot 9 + 4 \cdot (-1) \\ &= 0 \end{aligned}$$

Thus  $x = 2$  is a root.

Since both sides of the root have negative function values, the algorithm will only bounce around without converging to this root. This can be formalized via the intermediate value theorem.

e) The python implementation is essentially already given in the lecture slides, so I will do it in Uiua.

The screenshot shows the Uiua programming language interface. At the top, it says "Uiua A programming language for point-free enjoyers" with links for "Support Uiua's development" and "Home". Below this is a code editor with a dark background and colorful syntax highlighting. The code implements a bisection algorithm to find a root of a function  $f$  within a given interval  $[a, b]$  with a tolerance  $tol$ .

```

1 f ← ++⊃(
2   x⊃(~-1~n3|n2)
3   | x4x⊃(-1|~n3)
4   | x4~-1)
5
6 Bisection ← (
7   ⊃⊃-+⊃⊃(÷2/+)-⊃-1⊃⊃⊃⊃(
8     ⊃⊃⊃⊃(±f)
9     =⊃⊃⊃⊃(⊃⊃)
10  ) ⊃⊃((±f)÷2+)|
11 )
12 ∇(Bisection|>tol a b)
13
```

The output of the program is shown at the bottom:  $0.000732421875$  and  $-0.00048828125$ . To the right of the output, it says  $\frac{b}{a} \Rightarrow$  we approach 0. A "Run" button is visible on the right side of the output area.

Note: Uiua is not yet stable  
Uiua 0.17.0-rc.2

Problem 2 Consider

$$f(x) = x^3 + x - 1 = 0.$$

$$a) \quad f(-1) = (-1)^3 - 1 - 1 = -3 < 0,$$

$$f(1) = 1^3 + 1 - 1 = 1 > 0$$

Since  $f \in C[-1, 1]$ , from I.V.T.

there must be some  $r \in [-1, 1]$  with

$$f(r) = 0.$$

Additionally,  $f'(x) = 3x^2 + 1 > 0 \quad \forall x \in \mathbb{R}$

So  $f$  is nondecreasing, meaning the root  $r$  is unique.  $\square$

$$b) \quad 6. \quad x = x_0$$

$$8. \quad x_{\text{new}} = g(x)$$

$$9. \quad \text{if } \sim \leq 1e-6 \quad \# \quad |E| \leq tol$$

$$11. \quad x = x_{\text{new}}$$

The comment addresses the fact that  $f(x_0)$  did not converge in the given iteration time. Thus, the returned  $x$ -value could be radically different from  $x_{\text{new}}$  and does not represent the proper fix-point value of  $f(x_0)$ , if it exists.

To calculate the upper bound of the error we use the a posteriori error bound

$$|x_k - r| \leq L^k |x_0 - r|,$$

where  $r$  is the convergent value,

and  $|g'(x)| \leq L < 1$  for  $k$  iterations.

$$g'(x) = \left( \frac{1}{1+x^2} \right)' = \frac{-2x}{(1+x^2)^2} \leq \frac{-2x_0}{(1+x_0^2)^2} < 1,$$

$$\text{So let } L = \frac{2x_0}{(1+x_0^2)^2}, \quad x_0 = 1/2, \quad r = 0$$

$$\begin{aligned} \text{then } |E| &\leq (1 + 2^2)^{-2k} \cdot \frac{1}{2} = (5/4)^{-2k} \cdot \frac{1}{2} \\ &= \underline{\underline{\frac{1}{2} (4/5)^{2k}}} \end{aligned}$$

Problem 3 Let for  $a \in \mathbb{R}$

$$\phi_a(x) = (x^3 - 3ax^2 - 1)^2 + (3ax^2 - a^3)^2$$

a) let  $x_0 = 0.75 = 3/4$ ,  $a = 0$ :

$$\phi_0(x) = (x^3 - 1)^2$$

$$\Rightarrow \phi'_0(x) = 6x^2(x^3 - 1) = 6x^5 - 6x^2$$

first iteration:

$$\begin{aligned}\phi_0(x_0) &= \left(\left(\frac{3}{4}\right)^3 - 1\right)^2 = \left(\frac{27}{64} - 1\right)^2 \\ &= \left(-\frac{37}{64}\right)^2 = \frac{1369}{4096} \approx 0.334\end{aligned}$$

$$\begin{aligned}\phi'_0(x_0) &= 6\left(\frac{3}{4}\right)^5 - 6\left(\frac{3}{4}\right)^2 \\ &= 6 \cdot \frac{243}{1024} - 6 \cdot \frac{9}{16} \\ &= 6 \left( \frac{243 - 576}{1024} \right) \\ &= 6 \left( \frac{-233}{1024} \right) \\ &= -\frac{699}{512} \approx -1.37\end{aligned}$$

$$\begin{aligned}\Rightarrow x_1 &= x_0 - \phi_0(x_0) : \phi'_0(x_0) \\ &= \frac{3}{4} + \frac{1369}{4096} \cdot \frac{512}{699} \\ &= \frac{5563}{5592} \approx 0.995\end{aligned}$$

This is  
wrong

Second iteration:

$$\begin{aligned}\phi_0(x_1) &= \left(\left(\frac{5563}{5592}\right)^3 - 1\right)^2 = \frac{7324850714133791881}{30577570518753817657344} \\ &\approx 0.000240\end{aligned}$$



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Run

Ulua 0.17.0-rc.2



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Run

Ulua 0.17.0-rc.2



$$\text{Let } F: \mathbb{R}^2 \rightarrow \mathbb{R}^2,$$

$$(x, y) \mapsto (x^3 - 3xy^2 - 1, 3x^2y - y^3)$$

b) Show that

$$(x^3 - 3xy^2 - 1)^2 + (3x^2y - y^3)^2 = 0 \quad : X$$

$$\Leftrightarrow x^3 - 3xy^2 - 1 = 0 \wedge 3x^2y - y^3 = 0 \quad : Y$$

i) assume  $Y$ , show  $X \Leftarrow Y$ :

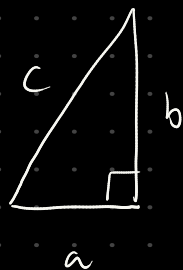
$$0^2 + 0^2 = 0 \quad \underline{\text{Ok}}$$

ii) assume  $X$ , show  $X \Rightarrow Y$ :

by pythagorean theorem,

if  $c$  is to be zero, both

$a$  and  $b$  must be too. Ok



c) recall  $J(x, y) = D F(x, y)$

$$\Rightarrow J(x, y) = \begin{bmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_2}{\partial x} \\ \frac{\partial F_1}{\partial y} & \frac{\partial F_2}{\partial y} \end{bmatrix}$$

$$= \begin{bmatrix} 3x^2 - 3y^2 & 6xy \\ -6xy & 3x^2 - 3y^2 \end{bmatrix}, \text{ then}$$

$$\begin{bmatrix} x \\ y \end{bmatrix}_{k+1} = \begin{bmatrix} x \\ y \end{bmatrix}_k - J(x_k, y_k)^{-1} F(x_k, y_k),$$

because we can generalize newton's method through first-order taylor expansion of  $F_1$  and  $F_2$  s.t.

$$F_1(x, y) \approx F_1(x_k, y_k) + \frac{\partial F_1}{\partial x}(x - x_k) + \frac{\partial F_1}{\partial y}(y - y_k)$$

and similarly for  $F_2$ .

Analogous to the tangent lines of scalar newton's method, these are the tangent planes to our surfaces  $F_1$  and  $F_2$ . We just established that these need to be zero, so

$$F_1(x_k, y_k) + \frac{\partial F_1}{\partial x}(x - x_k) + \frac{\partial F_1}{\partial y}(y - y_k) = 0 \\ \wedge F_2(x_k, y_k) + \frac{\partial F_2}{\partial x}(x - x_k) + \frac{\partial F_2}{\partial y}(y - y_k) = 0$$

$$\Leftrightarrow F \begin{bmatrix} x_k \\ y_k \end{bmatrix} + \underbrace{\begin{bmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} \end{bmatrix}}_{\text{Jacobian}} \begin{bmatrix} x - x_k \\ y - y_k \end{bmatrix} = \vec{0}$$

$$\Leftrightarrow \begin{bmatrix} x - x_k \\ y - y_k \end{bmatrix} = -J^{-1}(x_k, y_k) F(x_k, y_k)$$

$$\Leftrightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}_k - J^{-1}(x_k, y_k) F(x_k, y_k)$$

Where  $\begin{bmatrix} x \\ y \end{bmatrix}$  is a point we can

use further so  $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}_{k+1}$   $\square$

$$d) \quad F(x, y) = 0 \Leftrightarrow F_1(x, y) = 0 \\ \wedge F_2(x, y) = 0$$

$$3x^2y = y^3 \Leftrightarrow x = \pm \sqrt{\frac{1}{3} y^2} \\ = \pm \frac{\sqrt{3}}{3} y \quad \wedge y \neq 0$$

$$\rightarrow \left( \pm \frac{\sqrt{3}}{3} y \right)^3 \mp \sqrt{3} y^3 = 1$$

$$\Leftrightarrow y^3 \left( \pm \left( \frac{\sqrt{3}}{3} \right)^3 \mp \sqrt{3} \right) = 1$$

$$\Leftrightarrow y = \sqrt[3]{\frac{1}{\left( \pm \left( \frac{\sqrt{3}}{3} \right)^3 \mp \sqrt{3} \right)}} = \pm \frac{\sqrt{3}}{2}$$

$$\rightarrow x = \pm \sqrt{\frac{1}{3} \frac{3}{4}} = \pm \frac{1}{2}$$

Yields four candidates:

$$F\left(\frac{1}{2}, \frac{\sqrt{3}}{2}\right) \neq 0$$

$$F\left(\frac{-1}{2}, \frac{\sqrt{3}}{2}\right) = 0$$

$$F\left(\frac{1}{2}, \frac{-\sqrt{3}}{2}\right) \neq 0$$

$$F\left(\frac{-1}{2}, \frac{-\sqrt{3}}{2}\right) = 0$$

but also

$$y=0 \Rightarrow x=1,$$

so check

$$F(1, 0) = 0$$

e) Again I turn to the moon-runes of Uiua:

```

1 # Experimental!
2 ~ "git: github.com/Omnikar/uiua-math" ~ MInv Mvp
3
4 # ? y x
5 F ← ⌋(
6   -⌋(n3 | x3 × o n2)
7   | -1 -⌋(x3 × n2 | n3 • o))
8 # ? a x
9 φ ← + n2 F
10 # ? y x
11 J ← ⌋[
12   ⌋[x3 - n2 | x6 ×]
13   | ⌋[x - 6 × | x3 - n2]]
14
15 # ? f f' x0
16 Newton!! ← ->(÷ ⌋^1^0)
17 # ? x+yi
18 VectorNewton ← ->(/c ~ Mvp BF°c ~ (MInv J°c))
19
20 $first ÖVectorNewton1 ~c0.8 0.1
21 $second ÖVectorNewton2 ~c0.8 0.1
22 $first ÖVectorNewton1 ~c-0.6 0.7
23 $second ÖVectorNewton2 ~c-0.6 0.7
24 $first ÖVectorNewton1 ~c-0.6 -0.7
25 $second ÖVectorNewton2 ~c-0.6 -0.7
26
# iteration
first: 1.0303747534516765-0.0595660749506903i
second: 0.9977562079241812-0.00365085084939442i
first: -0.45997693194925027+0.8542099192618224i
second: -0.5015799675805404+0.8651358310710837i
first: -0.45997693194925027-0.8542099192618224i
second: -0.5015799675805404-0.8651358310710837i

```

Note: Uiua is not yet stable

Run

$(0.8, 0.1)$

$(-0.6, 0.7)$

$(-0.6, -0.7)$

$(1, 0)$

$(-\frac{1}{2}, \frac{\sqrt{3}}{2})$

$(-\frac{1}{2}, -\frac{\sqrt{3}}{2})$

I represent a vector as a complex number, so the output shows  $x + yi$ .

f) Using the above implementation  
(it is already in  $\mathbb{R}^2$ ) :

Check  
if it is  
root

```
15 # ? f f' x0
16 Newton!! ← →(÷^1^0)
17 # ? x+yi
18 VectorNewton ← →(/c~Mvp EF°c →(MInv J°c))
19
20 .öVectorNewton100 ~c0.5 0.5
21 →[-1/2 ÷2√3] ~c°c
22
    -0.5+0.8660254037844386i
    1
```

Converges to  
 $(-\frac{1}{2}, \frac{\sqrt{3}}{2})$

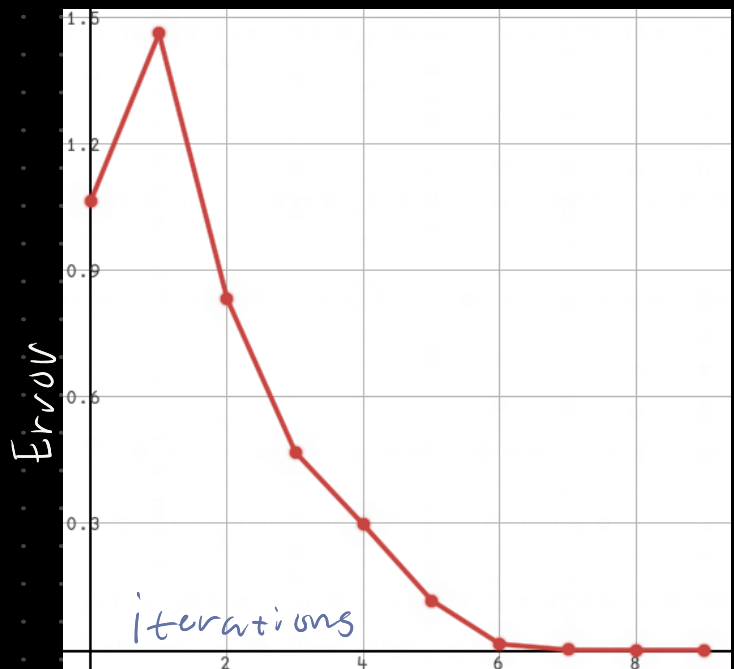
Run

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Uiua 0.17.0-rc.2

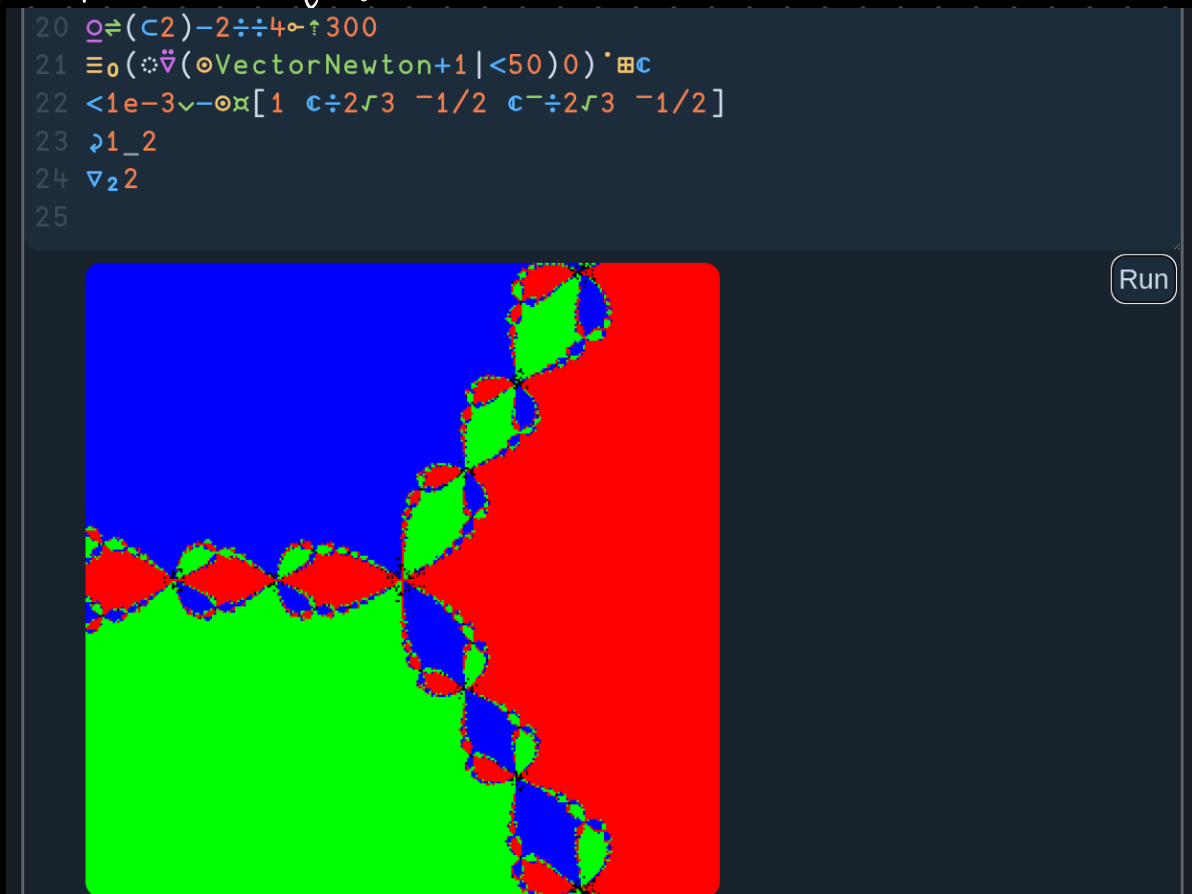
```
21 Plot Data!(
22   ↑10
23   New →(
24     ✓-c÷2√3 -1/2 ≡(
25       öVectorNewton(→c0.5 0.5)|
26     )
27   )
28 )
29
```

```
1 # Experimental!
2 ~ "git: github.com/Omnikar/uiua-math" ~ MInv Mvp
3 ~ "git: github.com/Omnikar/uiua-plot" ~ Data Plot
```



The plot shows a stable convergence.  
my hunch tells me it converges  
linearly :)

g) Here's the newton fractal:



We can observe a few black spots because they don't converge in 50 iterations.

Note: this computation is slow because I am not terminating early (so 50 iterations per pixel).

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That's it. I didn't get time for 1f) or 2c).

Also the fact that I didn't use python.